

How to control HD44780-based Character-LCD

(Industry-Standard-Character-LCD) Code-examples for PIC16C84

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4.1. Basic control software

Microchip's AN587 was used as a basis for this code.

WARNING:

Microchip's AN587 has major errors in the **read from** LCD code sequences.
The routines on this page use the correct *read from* LCD code sequences.

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4.1.1. Requirements / features

- HD44780-based (industry-standard) character-LCD, all software in this chapter is based on it's instruction-set.
- PIC16C84 running on a 4MHz crystal, some code is based on this frequency.
- 8-bit interface between microcontroller and LCD-module.

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4.1.2. Global declarations

To get things working.

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4.1.2.1. Register declarations

Purpose:

- Tells MPASM which ports and registers (files) to use.

Code:

```
LCD_DATA EQU      PORTB      ; LCD data lines interface
LCD_DATA_TRIS EQU   TRISB
LCD_CTRL EQU      PORTA      ; LCD control lines interface

LCD_TEMP EQU      0x020      ; LCD subroutines internal use

DELAY EQU         0x023      ; Used in DELAYxxx routines
X_DELAY EQU       0x024      ; Used in X_DELAYxxx routines
```

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4.1.2.2. Literal declarations

Purpose:

- Literal declarations (Equates) used in the code.

Code:

```
; PORTA control bits
LCD_E EQU         2          ; LCD Enable control line
LCD_RW EQU        1          ; LCD Read/Write control line
LCD_RS EQU        0          ; LCD Register-Select control line
```

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4.1.2.3. Procedure declarations / library interface

Since MPLIB and MPLINK are not yet available, no declarations are needed.

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4.1.3. Code

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4.1.3.1. LCD initialisation

Purpose:

- LCD initialisation code to be executed after power-up (i.e.: before any other subrou
- Should be modified to your needs (i.e. display type, cursor on/off, etc.)

Code:

```
LCDINIT
                                ; Busy-flag is not yet valid
                                ; ALL PORT output should output Low.
                                ; power-up delay
CLRFB    LCD_CTRL
MOVLW    0x01E
CALL     X_DELAY500            ; 30 * 0.5mS = 15mS
                                ; Busy Flag should be valid from here
                                ; 8-bit-interface, 2-lines
MOVLW    0x038
CALL     LCDPUTCMD
MOVLW    0x000                ; disp.off, curs.off, no-blink
CALL     LCDDMODE
CALL     LCDCLEAR
MOVLW    0x004                ; disp.on, curs.off
CALL     LCDDMODE
MOVLW    0x002                ; auto-inc (shift-cursor)
CALL     LCDEMODE
RETURN
```

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4.1.3.2. Busy flag

Purpose:

- Tests if the LCD is busy. Returns when LCD busy-flag is inactive.

Code:

```
LCDBUSY
BSF       STATUS,RP0           ; Select Register page 1
MOVLW     0x0FF                ; Set PORTB for input
MOVWF     LCD_DATA_TRIS
BCF       STATUS, RP0         ; Select Register page 0
BCF       LCD_CTRL, LCD_RS; Set LCD for command mode
BSF       LCD_CTRL, LCD_RW; Setup to read busy flag
BSF       LCD_CTRL, LCD_E      ; LCD E-line High
MOVF      LCD_DATA, W          ; Read busy flag + DDram address
BCF       LCD_CTRL, LCD_E      ; LCD E-line Low
ANDLW     0x80                 ; Check Busy flag, High = Busy
BTFSS     STATUS, Z
GOTO      LCDBUSY
LCDNOTBUSY
BCF       LCD_CTRL, LCD_RW
BSF       STATUS, RP0         ; Select Register page 1
MOVLW     0x000
MOVWF     LCD_DATA_TRIS       ; Set PORTB for output
BCF       STATUS, RP0         ; Select Register page 0
RETURN
```

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4.1.3.3. Clear display

Purpose:

- Clears display and returns cursor to home position (upper-left corner).

Code:

```

LCDCLEAR
    MOVLW    0x001
    CALL     LCDPUTCMD
    RETURN

```

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4.1.3.4. Cursor home

Purpose:

- Returns cursor to home position.
- Returns display to original position (when shifted).

Code:

```

LCDHOME
    MOVLW    0x002
    CALL     LCDPUTCMD
    RETURN

```

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4.1.3.5. Entry mode

Purpose:

- Sets entry mode of the LCD
- Required entry mode must be set in W
 - b0 : 0 = no display shift, 1 = display shift
 - b1 : 0 = auto-decrement, 1 = auto-increment
 - b2-b7 : don't care

Code:

```

LCDEMODE
    ANDLW    0x003           ; Strip upper bits
    IORLW    0x004           ; Function set
    CALL     LCDPUTCMD
    RETURN

```

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4.1.3.6. Display mode

Purpose:

- Sets display control
- Required entry mode must be set in W
 - b0 : 0 = cursor blink off, 1 = cursor blink on (if b1 = 1)
 - b1 : 0 = cursor off, 1 = cursor on
 - b2 : 0 = display off, 1 = display on (display data remains in DD-RAM)
 - b3-b7 : don't care

Code:

```

LCDDMODE
    ANDLW    0x007           ; Strip upper bits
    IORLW    0x008           ; Function set
    CALL     LCDPUTCMD
    RETURN

```

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4.1.3.7. Set character generator RAM address

Purpose:

- Sets the Character-Generator-RAM address. CGRAM data is read/written after this setting.
- Required CGRAM address must be set in W
 - b0-5 : required CGRAM address
 - b6-7 : don't care

Code:

```

LCDSCGA
        ANDLW    0x03F           ; Strip upper bits
        IORLW    0x040           ; Function set
        CALL     LCDPUTCMD
        RETURN

```

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4.1.3.8. Set display data RAM address**Purpose:**

- Sets the Display-Data-RAM address. DDRAM data is read/written after this setting.
- Required entry mode must be set in W
 - b0-6 : required DDRAM address
 - b7 : don't care

Code:

```

LCDSDDA
        IORLW    0x080           ; Function set
        CALL     LCDPUTCMD
        RETURN

```

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4.1.3.9. Get address counter contents**Purpose:**

- Returns address counter contents, used for both DDRAM and CGRAM.
- RAM address is returned in W

Code:

```

LCDGADDR
        BSF      STATUS,RP0      ; Select Register page 1
        MOVLW    0x0FF           ; Set PORTB for input
        MOVWF    LCD_DATA_TRIS
        BCF      STATUS, RP0     ; Select Register page 0
        BCF      LCD_CTRL, LCD_RS; Set LCD for command mode
        BSF      LCD_CTRL, LCD_RW; Setup to read busy flag
        BSF      LCD_CTRL, LCD_E  ; LCD E-line High
        MOVF     LCD_DATA, W      ; Read busy flag + RAM address
        BCF      LCD_CTRL, LCD_E  ; LCD E-line Low
        ANDLW    0x07F           ; Strip upper bit
        BCF      LCD_CTRL, LCD_RW
        BSF      STATUS, RP0     ; Select Register page 1
        MOVLW    0x000
        MOVWF    LCD_DATA_TRIS   ; Set PORTB for output
        BCF      STATUS, RP0     ; Select Register page 0
        RETURN

```

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4.1.3.10. Write character**Purpose:**

- Sends character to LCD
- Required character must be in W

Code:

```

LCDPUTCHAR
    MOVWF    LCD_TEMP ; Character to send is in W
    CALL     LCDBUSY   ; Wait for LCD to be ready
    BCF      LCD_CTRL, LCD_RW; Set LCD in read mode
    BSF      LCD_CTRL, LCD_RS; Set LCD in data mode
    BSF      LCD_CTRL, LCD_E ; LCD E-line High
    MOVF     LCD_TEMP, W
    MOVWF    LCD_DATA ; Send data to LCD
    BCF      LCD_CTRL, LCD_E ; LCD E-line Low
    RETURN

```

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4.1.3.11. Write command

Purpose:

- Sends command to LCD
- Required command must be in W

Code:

```

LCDPUTCMD
    MOVWF    LCD_TEMP ; Command to send is in W
    CALL     LCDBUSY   ; Wait for LCD to be ready
    BCF      LCD_CTRL, LCD_RW; Set LCD in read mode
    BCF      LCD_CTRL, LCD_RS; Set LCD in command mode
    BSF      LCD_CTRL, LCD_E ; LCD E-line High
    MOVF     LCD_TEMP, W
    MOVWF    LCD_DATA ; Send data to LCD
    BCF      LCD_CTRL, LCD_E ; LCD E-line Low
    RETURN

```

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4.1.3.12. Delay loops

Purpose:

- Used in LCDINIT subroutine
- Required delay factor must be in W
(Could be coded more efficient, but this approach gives more flexibility)

Code:

```

;***** a 500uS delay @ 4MHz X-tal
DELAY500 MOVLW    D'165'          ; +1          1 cycle
          MOVWF    DELAY          ; +2          1 cycle
DELAY500_LOOP DECFSZ DELAY, F ; step 1 1 cycle
          GOTO     DELAY500_LOOP ; step 2 2 cycles
DELAY500_END   RETURN            ; +3          2 cycles

;***** a delay of 'W' * 500mS
X_DELAY500     MOVWF    X_DELAY    ; +1          1 cycle
X_DELAY500_LOOP CALL     DELAY500 ; step1      wait 500uSec
          DECFSZ    X_DELAY, F ; step2          1 cycle
          GOTO     X_DELAY500_LOOP ; step3      2 cycles
X_DELAY500_END RETURN            ; +2          2 cycles

```

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4.1.4. Availability

[LCD-PIC.ZIP](#): an example using some of the above subroutines (all subroutines are included). Source is coded for a 4*20 LCD, adjust it to your needs!

Shows the following screen on a 4*20 LCD:

```

-----
|This is on line : 0|
|This is on line : 1|
|This is on line : 2|
|This is on line : 3|
-----

```

Shows the following screen on a 2*40 LCD:

```

-----
|This is on line : 0This is on line : 2|
|This is on line : 1This is on line : 3|
-----

```

Shows the following screen on a 2*20 LCD:

```

-----
|This is on line : 0|
|This is on line : 1|
-----

```

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4.2. Advanced control software

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4.2.1. User defined characters

Purpose:

After several requests a quick explanation on how to implement user-defined characters:

First you'll need to make a pixel definition for the characters you want to use. This is the pixel definition for an underlined '0' (char code 0x30) based on a 5x7 dots character definition:

row	bits 76543210	byte value
000	xxx	0x0E
001	x x	0x11
010	x xx	0x13
011	x x x	0x15
100	xx x	0x19
101	x x	0x11
110	xxx	0x0E
111	xxxxx	0x1F

The byte values need to be loaded into CGRAM address 00ccrrrr (binary), where:

- ccc = user-defined character number (0...7)
- rrr = row number of the user defined character (0...7)

Once that's done you can write character codes 0...7 to the desired LCD character position, just like you do with 'normal' characters.

User-defined character definitions may be changed 'on-the-fly'.

Code:

(More detailed code may be published some day)

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Mail me your ideas!

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4.3. Used hardware

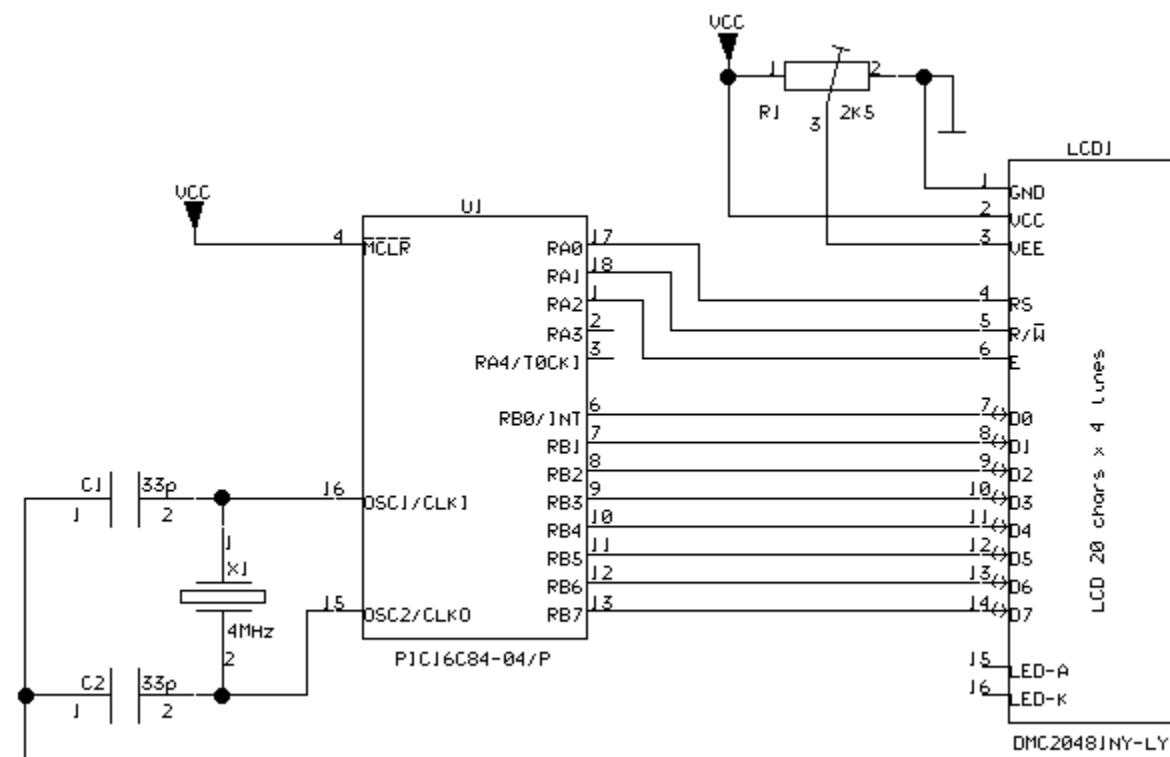
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4.3.1 Controller

- A PIC16C84 is used to control the LCD.
- 8-bit data interface between controller and LCD.

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4.3.2 LCD hardware interface



[Shift-Click to download gif.](#)

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4.4. Development environment

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4.4.1. Software

- Assembler: MPASM V1.30
 - Programmer software: PICSTART 16B1 V5.00.00
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-

4.4.2. Hardware

- Programmer PICSTART 16B1 (firmware V2.00)
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